

**Amendments to the Claims**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (Previously presented) A dummy instrument for use in a simulator, the instrument comprising:  
a control body with user manipulatable angulation control, an insertion tube and an umbilical  
extending from the control body, and at least one angulation cable extending from the user  
manipulatable angulation control, and down the umbilical, the umbilical being releasably  
attached to a main unit, a motor within the instrument at a distal end of the umbilical to apply a  
variable force to the cable, and a position detector within the instrument to detect the angular  
position of the angulation control.
2. (Original) An instrument according to claim 1, wherein the position detector measures the  
rotation of the control.
3. (Original) An instrument according to claim 1, wherein the position detector measures the  
displacement of the cable.
4. (Original) An instrument according to claim 3, wherein the position detector is located at the  
distal end of the umbilical.
5. (Previously presented) An instrument according to 1, wherein the instrument is provided with  
two pairs of angulation cables each pair forming a loop around the control body, and around a  
respective motor at the distal end of the umbilical.
6. (Previously presented) An instrument according to claim 5, wherein means are provided to  
retension each of the loops.

7. (Previously presented) An instrument according to claim 1, wherein a connector at the distal end of the umbilical is configured to provide a two-part release, allowing release to a partially released position in which the umbilical may be rotated relative to the base unit, but in which the weight of the umbilical is still supported by the base unit, and a second fully released position in which the umbilical is completely releasable from the base unit.

8. (Previously presented) An instrument according to claim 1, wherein the position of each angulation cable is sensed by a combination of a low resolution absolute position detector and a higher resolution incremental encoder.